

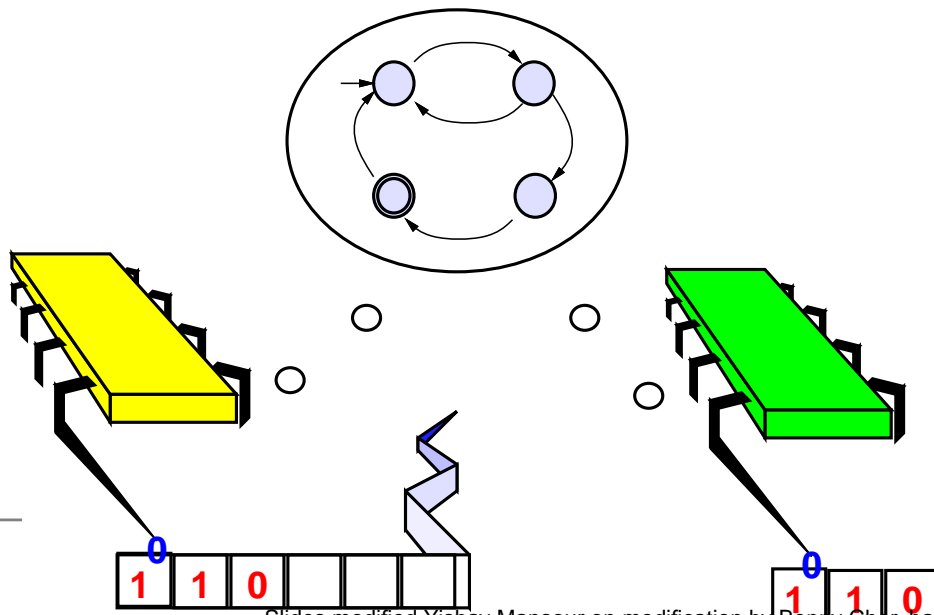
Computational Models: Lecture 10, Spring 2011

- Linear Bounded Automata
- Unrestricted Grammar
- Introduction to Time Complexity

- Sipser's book, Chapter 5, Sections 5.3 and Chapter 7, Section 7.1

Linear Bounded Automata

- A restricted form of TM.
- Cannot move off portion of tape containing input
- Details: Has special letters for start and end input, which it can not modify.
- Can not move left (right) of the left (right) mark.
- Size of input determines size of memory



Linear Bounded Automata

Question: Why **linear**?

Answer: Using a **tape alphabet** larger than the **input alphabet** increases memory by a constant factor.

Linear Bounded Automata

Believe it or not, LBAs are quite powerful.

The **deciders** for

- A_{DFA} (does a DFA accept a string?)
- A_{CFG} (is string in a CFG?)
- $\text{EMPTY}_{\text{DFA}}$ (is a DFA trivial?)
- $\text{EMPTY}_{\text{CFG}}$ (is a CFL empty?)

are all **LBAs**.

Every CFL can be decided by a LBA.

Not too easy to find a **natural, decidable language** that **cannot be decided** by an LBA.

Acceptance for LBAs

Define

$$A_{\text{LBA}} = \{\langle M, w \rangle \mid M \text{ is an LBA that accepts } w\}$$

Question: Is A_{LBA} decidable?

Answer: Unlike A_{TM} , the language A_{LBA} is decidable!

Lemma:

Let M be a LBA with

- q states
- g symbols in tape alphabet

On an input of size n , LBA has exactly qng^n distinct configurations, because a configuration involves:

- control state (q possibilities)
- head position (n possibilities)
- tape contents (g^n possibilities)

Theorem: A_{LBA} is decidable

Idea:

- Check that M is a valid LBA, if not **reject**.
- Simulate M on w
- But what do we do if M loops?
- Must detect looping and reject.
- M loops if and only if it repeats a configuration.
- **Why?** And is this also true of “regular” TMs?
- By pigeon hole, if our LBA M runs long enough, it must repeat a configuration!

Theorem: A_{LBA} is decidable

On input $\langle M, w \rangle$, where M is an LBA and $w \in \Sigma^*$,

1. Simulate M on w ,
2. while maintaining a **counter**.
3. Counter incremented by 1 per each **simulated step** (of M).
4. Keep simulating M for qng^n steps, or until it halts (whichever comes first)
5. If M has halted, **accept** w if it was accepted by M , and **reject** w if it was rejected by M .
6. **reject** w if counter limit reached (M has not halted).

More LBAs

Surprisingly though, LBAs do have undecidable problems too!

Here is a related problem.

$$\text{Non-EMPTY}_{\text{LBA}} = \{\langle M \rangle \mid M \text{ is an LBA and } L(M) \neq \emptyset\}$$

Question: Is $\text{Non-EMPTY}_{\text{LBA}}$ decidable?

Non-EMPTY_{LBA}

$$\text{Non-EMPTY}_{\text{LBA}} = \{\langle M \rangle \mid M \text{ is an LBA and } L(M) \neq \emptyset\}$$

Theorem: Non-EMPTY_{LBA} is undecidable.

Proof by reduction from A_{TM} , using computation histories.

More LBAs

Given M and w , we will construct an LBA, B .

- $L(B)$ will contain exactly all accepting computation histories for M on w .
- M accepts w iff $L(B) \neq \emptyset$.

More LBAs

It is **not** enough to show that B exists.

We must show that the mapping from $\langle M, w \rangle$ to $\langle B \rangle$ is **computable**.

We are now going to describe the linear bounded machine, $\langle B \rangle$. It will be clear that indeed $\langle B \rangle$ is computable from $\langle M, w \rangle$.

Assume an accepting computation history is presented as a string:

$$\# \underbrace{\hspace{2cm}}_{C_1} \# \underbrace{\hspace{2cm}}_{C_2} \# \underbrace{\hspace{2cm}}_{C_3} \# \cdots \# \underbrace{\hspace{2cm}}_{C_\ell} \# ,$$

with descriptions of configurations separated by $\#$ delimiters.

The LBA

The LBA, B , works as follows:

On input x , the LBA B :

- breaks x according to the $\#$ delimiters
- identifies strings C_1, C_2, \dots, C_ℓ .
- then checks that **all** the following conditions hold:
 - Each C_i are a **configuration** of M
 - C_1 is the **start configuration** of M on w
 - Every C_{i+1} **follows** from C_i according to M
 - C_ℓ is an **accepting configuration**

The LBA

- Checking that each C_i is a **configuration** of M is easy: All it means is that C_i includes exactly one q symbols.
- Checking that C_1 is the start configuration on w , $q_0w_1w_2 \cdots w_n$, is easy, because the string w is “wired into” B .
- Checking that C_ℓ is an accepting configuration is easy, because C_ℓ must include the accepting state q_a .
- The only hard part is checking that each C_{i+1} follows from C_i by M 's transition function.

The Hard Part

Checking that for all i , C_{i+1} follows from C_i by M 's transition function:

- C_i and C_{i+1} **almost identical**, except for positions under head and adjacent to head.
- These positions should be updated according to transition function.

Do this verification by

- zig-zagging between corresponding positions of C_i and C_{i+1} .
- use “dots” on tape to mark current position
- all this can be done **inside space** allocated by input x .
Thus B is indeed a **LBA**.

Important!

The LBA, B , accepts the string x if and only if x equals an accepting computation history of M on w .

Therefore $L(B)$ is either **empty** or a singleton $\{x\}$.

We construct B so that $L(B)$ is **non-empty** iff M accepts w .

Thus $\langle M, w \rangle \in A_{\text{TM}}$ iff $\langle B \rangle \in \text{Non-EMPTY}_{\text{LBA}}$.

Namely $A_{\text{TM}} \leq_m \text{Non-EMPTY}_{\text{LBA}}$, so
 $\text{Non-EMPTY}_{\text{LBA}} \notin \mathcal{R}$.



BTW, is $\text{Non-EMPTY}_{\text{LBA}} \in \mathcal{RE}$?

Unrestricted Grammars

Unrestricted grammars are similar to context free ones, **except** left hand side of rules can be **strings of variables and terminal** with at least one variable.

- To **non-deterministically** generate a string according to a given **unrestricted grammar**:
 - Start with the initial symbol
 - While the string contains at least one non-terminal:
 - Find a substring that matches the LHS of some rule
 - Replace that substring with the RHS of the rule

Unrestricted Grammars: $\{a^n b^n c^n\}$

- Generate the variable sequence $L(ABC)^n$

$$S \rightarrow LT|\epsilon;$$

$$T \rightarrow ABCT|\epsilon;$$

- Sort the $\{A, B, C\}$ and get $LA^k B^k C^k$.

$$BA \rightarrow AB;$$

$$CB \rightarrow BC;$$

$$CA \rightarrow AC;$$

- Replace the variables by terminals. $LA \rightarrow a$;

$$aA \rightarrow aa;$$

$$aB \rightarrow ab;$$

$$bB \rightarrow bb;$$

$$bC \rightarrow bc;$$

$$cC \rightarrow cc;$$

Unrestricted Grammars

- Let UG be the set of languages that can be described by an Unrestricted Grammar:
- $UG = \{L : \exists \text{ Unrestricted Grammar } G \text{ such that } L[G] = L\}$
- Claim: $UG = RE$
- To Prove:
 - Show $UG \subseteq RE$
 - Show $RE \subseteq UG$

$UG \subseteq RE$

- Given any Unrestricted Grammar G , we create a 2-tape non-deterministic Turing Machine M that accepts $L[G]$.
- M maintains the input w on tape 1.
- M initializes tape 2 to the initial symbol S .
- In each iteration M does:
 - moves (non-deterministically) to some location on tape 2
 - Selects non-deterministically a rule R .
 - Tries to apply rule R to that location.
 - If successful, tests if tape 1 and tape 2 are identical.
 - If identical, terminates and **accepts**.
 - Otherwise, starts a new iteration.

$\mathcal{RE} \subseteq \mathcal{UG}$

- Given any language $L \in \mathcal{RE}$, let M be a **deterministic** Turing Machine that accepts it. We can create an Unrestricted Grammar G such that $L[G] = L$
 - Grammar: Generates a string
 - Turing Machine: Works from string to accept state
 - Two formalisms work in different directions
- Simulating Turing Machine with a Grammar by maintaining the TM configuration.
- Idea: variables of G are the states Q
 - Maintain $w[c]$, where w is the input and c is the current configuration.
 - if c is an accepting configuration, replace it by ϵ .

$\mathcal{RE} \subseteq \mathcal{UG}$

- Generate the string $w[q_0w]$.

$$S \rightarrow T[q_0]; T \rightarrow aTA_a | \epsilon$$

$$A_a[q_0 \rightarrow [q_0A_a; A_ab \rightarrow bA_a; A_a] \rightarrow a]$$

- Simulate TM M :

$$\delta(q, a) = (q', b, R) \Rightarrow qa \rightarrow bq';$$

$$\delta(q, a) = (q', b, L) \Rightarrow cqa \rightarrow q'cb; [qa \rightarrow [q'b$$

 $q] \rightarrow q\sqcup]$

- Accepting: derive from $w[uq_av]$ only w .

$$q_a \rightarrow E_L E_R$$

$$aE_L \rightarrow E_L; [E_L \rightarrow \epsilon$$

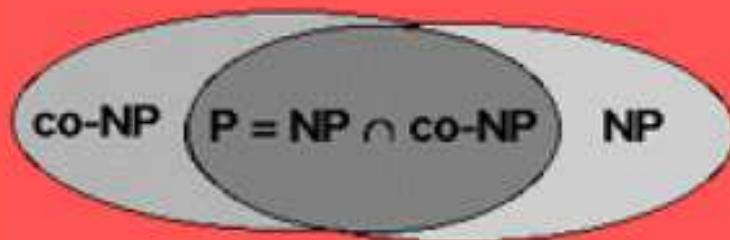
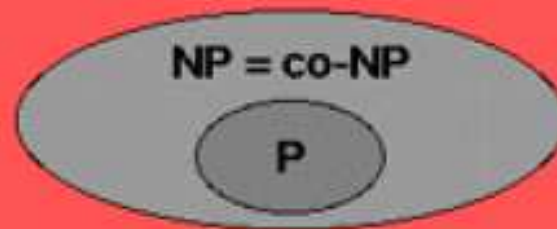
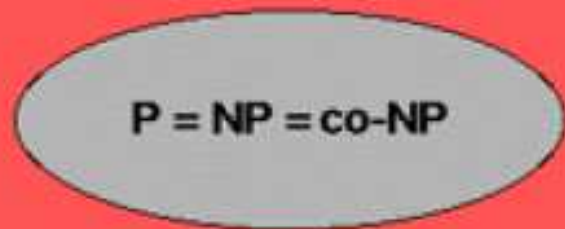
$$E_R a \rightarrow E_R; E_R] \rightarrow \epsilon$$

Ladies and Gentlemen, Boys and Girls

We are about to begin the third part of the course:

Introduction to Computational Complexity

Four Possible Relationships among Complexity Classes



Time Complexity

Consider

$$A = \{0^m 1^m \mid m \geq 0\}$$

Clearly this language is decidable.

Question: How much time does a **single-tape** TM need to decide it?

Time Complexity

M_1 : On input string w ,

1. Scan across tape and **reject** if **0** is found to the right of a **1**.
2. While both **0**s and **1**s appear on tape, repeat the following:
 - scan across tape, crossing of a single **0** and a single **1** in each pass.
3. If no **0**s and **1**s remain, **accept**, otherwise **reject**.

Analysis (1)

We consider the three stages separately. Let n denote the input length.

1. Scan across tape and **reject** if 0 is found to the right of a 1. If not, return to starting point.

- Scanning requires n steps.
- Re-positioning head requires n steps.
- Total is $2n = O(n)$ steps.

Analysis (2)

2. While both 0s and 1s appear on tape, repeat the following
 - scan across tape, crossing off a single 0 and a single 1 in each pass.
 - Each scan requires $O(n)$ steps.
 - Since each scan crosses off two symbols, the number of scans is at most $n/2$.
 - Total number of steps is $(n/2) \cdot O(n) = O(n^2)$.

Analysis (3)

3. If 0s still remain after all 1s have been crossed out, or vice-versa, **reject**. Otherwise, if the tape is empty, **accept**.

- Single scan requires $O(n)$ steps.
- Total is $O(n)$ steps.

Final Analysis

Total cost for stages

1. $O(n)$
2. $O(n^2)$
3. $O(n)$

which is $O(n^2)$

Deterministic Time

Let M be a deterministic TM, and let

$$t : \mathcal{N} \longrightarrow \mathcal{N}$$

We say that M runs in time $t(n)$ if

- For **every** input x of length n ,
- the number of steps that M uses,
- is **at most** $t(n)$.

Time Classes Definition

Let

$$t : \mathcal{N} \longrightarrow \mathcal{N}$$

be a function.

Definition:

$$\mathbf{DTIME}(t(n)) = \{L \mid L \text{ is a language, decided by an } O(t(n))\text{-time DTM}\}$$

Note that $t(n)$ run time is also required for strings that are **not in L** .

Do It Faster, Please

We have seen that

- $A = \{0^m 1^m \mid m \geq 0\}$,
- $A \in \text{DTIME}(n^2)$.

Can we do better, *i.e.* **faster**?

Home Improvement

M_2 : On input string w ,

1. Scan across tape and **reject** if **0** is found to the right of a **1**.
2. Repeat the following while both **0**s and **1**s appear on tape:
 - 2.1 scan across tape, checking whether total number of **0**s plus **1**s is even or odd. If odd, **reject**.
 - 2.2 Scan across tape, crossing off every other **0** (starting with the first), and every other **1** (starting with the first) in each pass.
3. If no **0**s or **1**s remain, **accept**, otherwise **reject**.

Analysis

First, we verify that M_2 indeed halts.

- on each scan in step 2.2,
 - The total number of 0s is cut in half,
 - and if there was a remainder, it is discarded.
 - Same for 1s.
- Example: start with 13 0s and 13 1s,
 - first pass: 6 0s and 6 1s are left
 - second pass: 3 0s and 3 1s are left
 - third pass: one 0s and one 1s are left
 - then no 0s and 1s are left.

Analysis

We now verify that M_2 is correct.

- Consider parity of 0s and 1s in 2.1,
- example: start with 13 0s and 13 1s
 - odd, odd (13)
 - even, even (6)
 - odd, odd (3)
 - odd, odd (1)
- The result, written right to left, is 1101, which is the binary representation of 13.
- Each pass checks equality of the next bit.
- Inequality in any specific bit will be detected (total number of 0s plus 1s will be odd).

Running Time Analysis

M_2 : On input string w ,

1. Scan across tape and **reject** if 0 is found to the right of a 1.
2. Repeat the following if both 0s and 1s appear on tape
 - 2.1 scan across tape, checking whether total number of 0s plus 1s is even or odd. If odd, **reject**.
 - 2.2 Scan across tape, crossing off every other 0 (starting with the first), and every other 1 (starting with the first).
3. If no 0s or 1s remain, **accept**, otherwise **reject**.

Running Time Analysis (cont.)

M_2 : On input string w ,

1. Scan across tape and **reject** if 0 is found to the right of a 1.
2. Repeat the following if both 0s and 1s appear on tape
 - 2.1 scan across tape, checking whether total number of 0s and 1s is even or odd. If odd, **reject**.
 - 2.2 Scan across tape, crossing off every other 0 (starting with the first), and every other 1 (starting with the first).
3. If no 0s or 1s remain, **accept**, otherwise **reject**.

- One pass in each stage (1, 2.1, 2.2, 3) takes $O(n)$ time.
- stage 1 and 3: each executed once
- 2.2 eliminates half of 0s and 1s: $1 + \log_2 n$ times
- total for 2 is $(1 + \log_2 n)O(n) = O(n \log n)$.
- grand total: $O(n) + O(n \log n) = O(n \log n)$.

Further Improvements, Anybody?

Question: Can the running time be made $o(n \log n)$?

Answer: Not on a **single tape** TM (proof on board).

Question:

But why do we have to stick with
single tape TMs?

Answer: We don't!

A Two Tape TM

M_3 : on input string w

1. Scan across tape and **reject** if **0** is found to the right of a **1**.
2. Scan across **0**s to first **1**, copying **0**s to tape 2.
3. Scan across **1**s on tape **1** until the end. For each **1**, cross off a **0**. If no **0**s left, *reject*.
- 4 If any **0**s left, *reject*, otherwise *accept*.

Question: What is the running time?

Complexity

Deciding $\{0^n 1^n\}$:

- single-tape M_1 : $O(n^2)$.
- single-tape M_2 : $O(n \log n)$ (fastest possible!).
- two-tape M_3 : $O(n)$.

Important difference between complexity and computability:

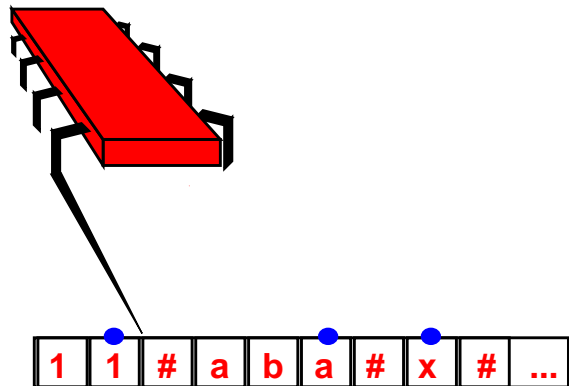
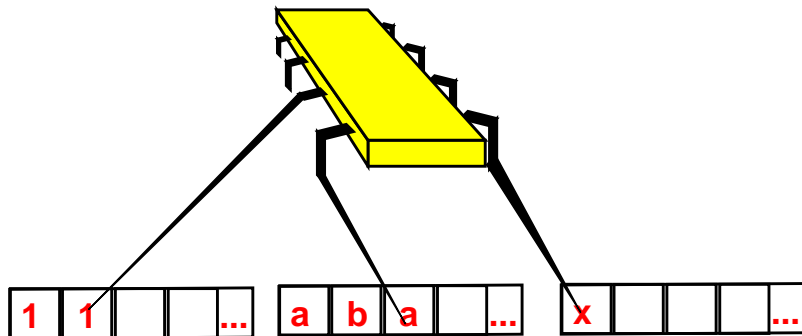
- Computability: all reasonable models **equivalent** (Church-Turing)
- Complexity: choice of model **does affect run-time**.

Q: By **how much** does model affect complexity?

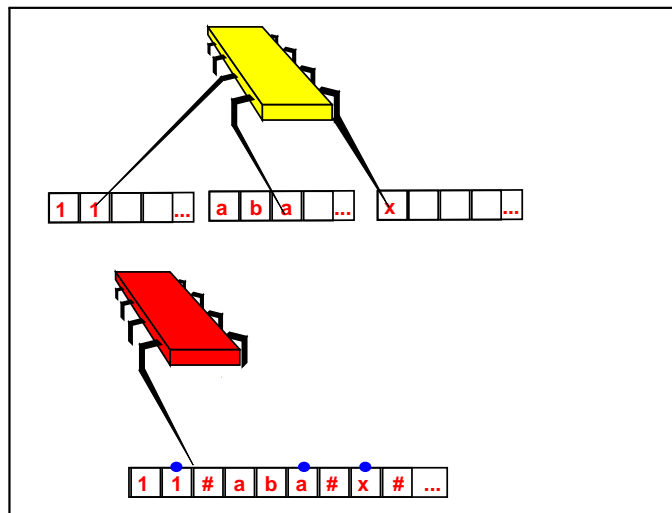
Models and Complexity

Let $t(n)$ be a function where $t(n) \geq n$, and let $L \subseteq \Sigma^*$ be a language.

Claim: If a $t(n)$ -time multitape TM decides L , then \exists an $O(t^2(n))$ -time single tape TM that decided L .



Reminder: Simulating MultiTape TMs



On input $w = w_1 \cdots w_n$, single tape S :

- puts on its tape $\# w_1 w_2 \cdots w_n \# \sqcup \# \sqcup \# \cdots \#$
- scans its tape from first $\#$ to $k + 1$ -st $\#$ to read symbols under “virtual” heads.
- rescans to write new symbols and move heads
- if S tries to move virtual head onto $\#$, then M takes “tape fault” and re-arranges tape.

Complexity of Simulation

For each step of M , S performs

- two scans
- up to k rightward shifts

On input of length n , M makes $O(t(n))$ many steps, so active portion of each tape is $O(t(n))$ long.

Total number of steps S makes:

- $O(t(n))$ steps to simulate **one step** of M .
- Total simulation $O(t(n)) \times O(t(n)) = O(t^2(n))$.
- Initial tape arrangement $O(n)$.
- Grand total: $O(n) + O(t^2(n)) = O(t^2(n))$ steps,
- under the reasonable assumption (**why?**) that $t(n) > n$.

Time Classes Definition, Again

Let

$$t : \mathcal{N} \longrightarrow \mathcal{N}$$

be a function.

Definition:

$$\mathbf{DTIME}(t(n)) = \{L \mid L \text{ is a language, decided by an } O(t(n))\text{-time TM}\}$$

Relations among Time Classes

Let $t_1, t_2 : \mathcal{N} \rightarrow \mathcal{N}$ be two functions.

- Claim: If $t_1(n) = O(t_2(n))$ then

$$\text{DTIME}(t_1(n)) \subseteq \text{DTIME}(t_2(n)) .$$

- Stated informally, more time does **not hurt**.
- But does it actually **help**?
- Claim: If $t_1(n) = O(t_2(n)/\log(n))$ then

$$\text{DTIME}(t_1(n)) \subsetneq \text{DTIME}(t_2(n)) .$$

- Informally, **sufficiently more** time **does help**.
- Proofs – sophisticated diagonalizations (omitted).

Non-Deterministic Time

Let N be a non-deterministic TM, and let

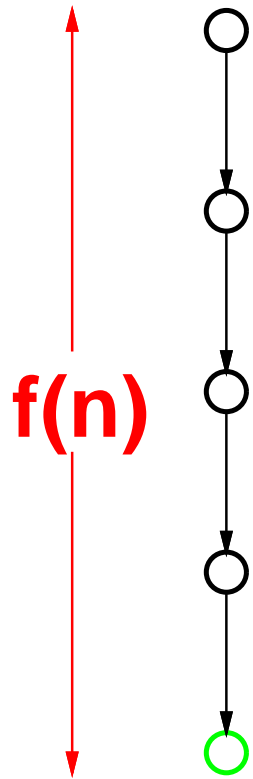
$$f : \mathcal{N} \longrightarrow \mathcal{N}$$

We say that N runs in time $f(n)$ if

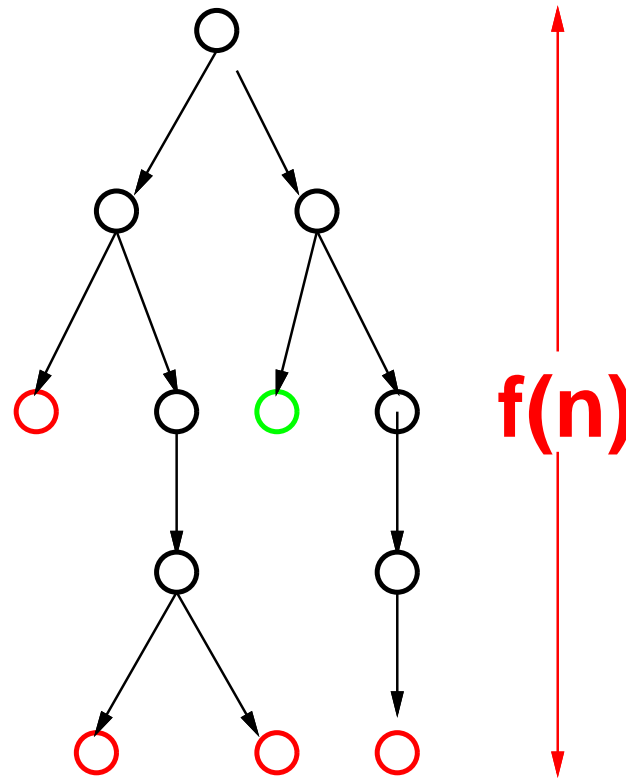
- For **every** input x of length n ,
- the **maximum** number of steps that N uses,
- on **any branch** of its computation tree on x ,
- is **at most** $f(n)$.

Deterministic vs. Non-Deterministic

deterministic



nondeterministic



Notice that **non-accepting** branches must **reject** within $f(n)$ many steps.

Models and Complexity

Claim: Suppose N is a **nondeterministic** TM that runs in time $t(n)$ and decides the language L .

Then there is an $2^{O(t(n))}$ -time **deterministic** TM, D , that decided L .

Note contrast with multi-tape result.

Simulation

Let N be a non-deterministic TM running in $t(n)$ time. Want to describe the deterministic TM, D , simulating N .

Basic idea of simulation:

- D tries all possible branches.
- If D finds any accepting state, it accepts.
- If all branches reject, D rejects.
- Notice N has **no looping branches**, so exactly one of two possibilities must occur.

Simulation Details

N 's computation is a tree:

- root is starting configuration,
- each node has bounded fanout $\leq b$ (why?),
- each branch has length $\leq t(n)$,
- total number of **leaves** at most $b^{t(n)}$,
- total number of **nodes** in tree $O(b^{t(n)})$,
- time to arrive from root to any node is $O(t(n))$.
- \implies Time to visit **all nodes** is

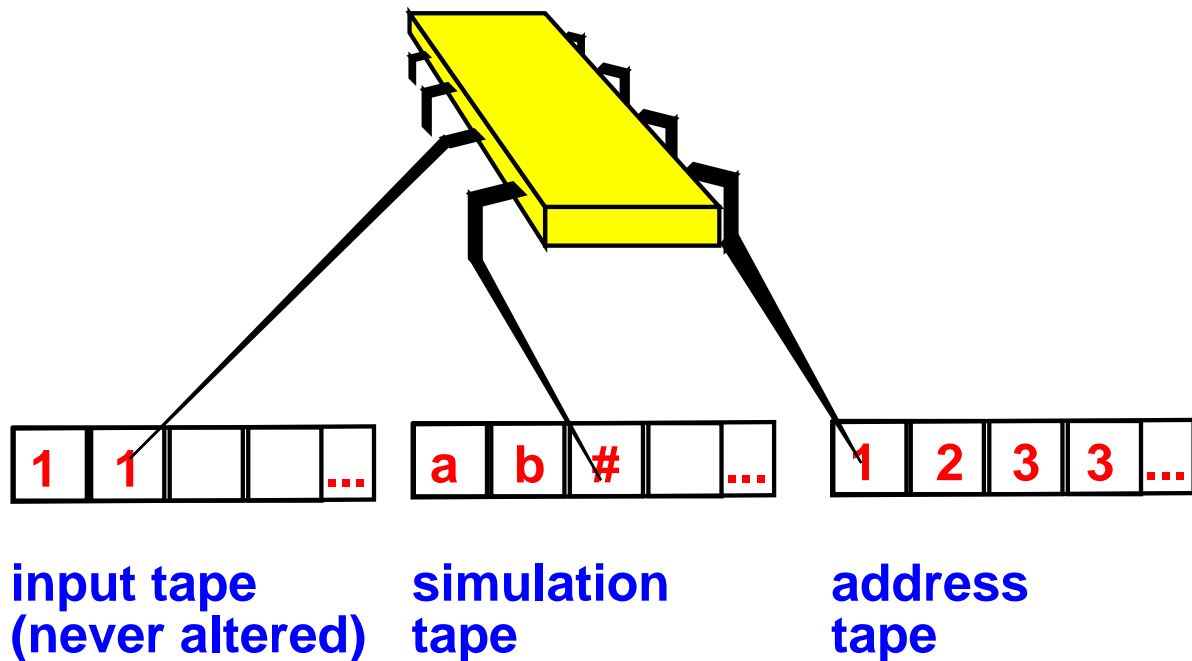
$$O\left(t(n) \times b^{t(n)}\right) = O\left(2^{O(t(n))}\right).$$

Remark

Breadth-first search used in simulation

- Inefficiently traverses from root to visit each node.
- Can be improved upon by using depth-first search (**why is it OK now?**) or other tree search strategies.
- Still, doing this may save constants, but nothing substantial (**why?**)

Remark



- Simulation uses three-tape machine.
- Single-tape simulation: $(2^{O(t(n))})^2 = 2^{O(2t(n))} = 2^{O(t(n))}$.

Important Distinction

- At most **polynomial** gap in time to perform tasks between different deterministic models (single- vs. multi-tape TMs, TM vs. **RAM**, etc.)
- compared to
- **Apparently exponential** gap in time to perform tasks between **deterministic** and **non-deterministic** models.

The Good, the Bad, and the Ugly

Complexity differences:
Polynomial is small; Exponential is large

	10	20	30	40	50	60
n	.00001 second	.00002 second	.00003 second	.00004 second	.00005 second	.00006 second
n^2	.00001 second	.00004 second	.00009 second	.00016 second	.00025 second	.00036 second
n^3	.00001 second	.00008 second	.027 second	.064 second	.125 second	.216 second
n^5	.1 second	3.2 seconds	24.3 seconds	1.7 minute	5.2 minutes	13.0 minutes
2^n	.001 second	1.0 second	17.9 minutes	12.7 days	35.7 years	366 centuries
3^n	.059 second	58 minutes	6.5 years	3855 centuries	$2 \cdot 10^8$ centuries	$1.3 \cdot 10^{13}$ centuries

Polynomial is Good, Exponential is Bad

Claim: All “reasonable” models of computation are polynomially equivalent.

Any one can simulate another with only **polynomial increase** in running time.

Question: Is a given problem solvable in

- **Linear** time? **model-specific**.
- **Polynomial** time? **model-independent**.
- We are interested in computation, not in models *per se*!