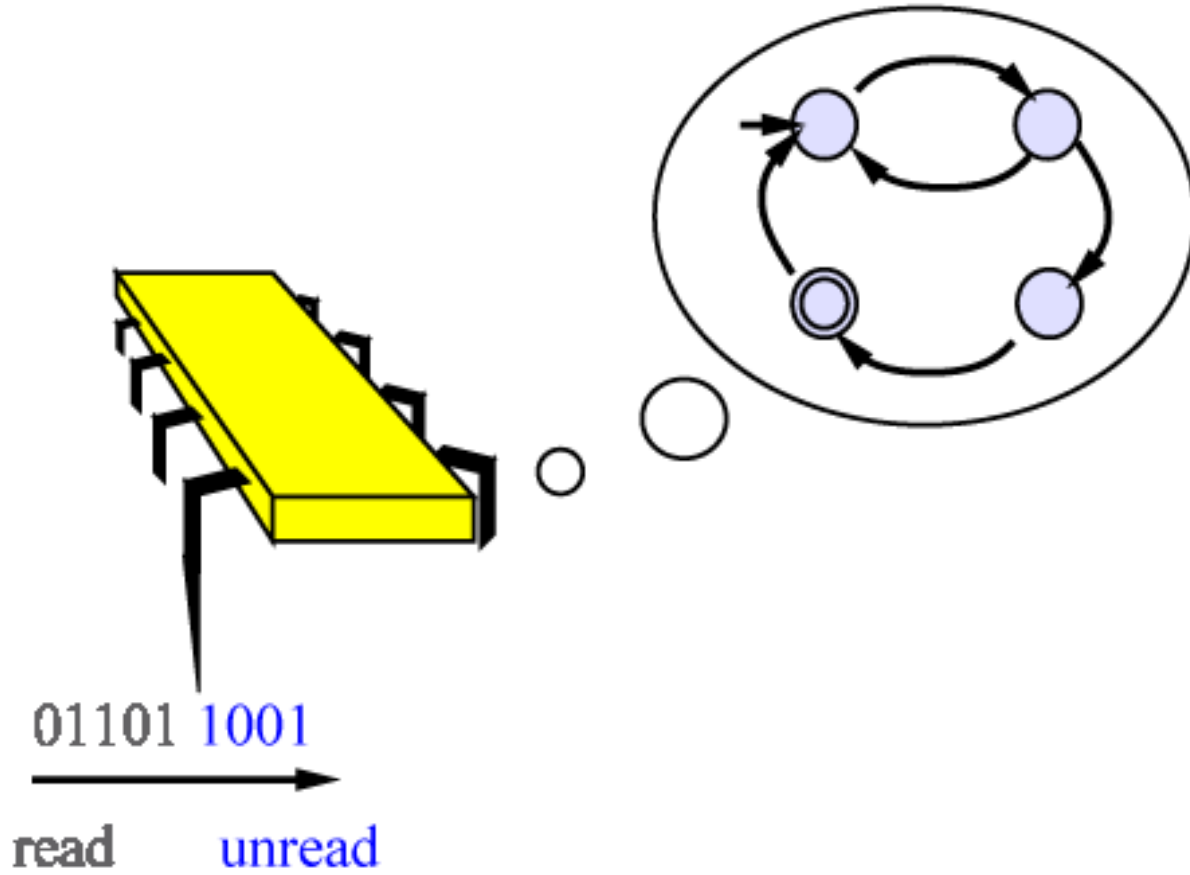


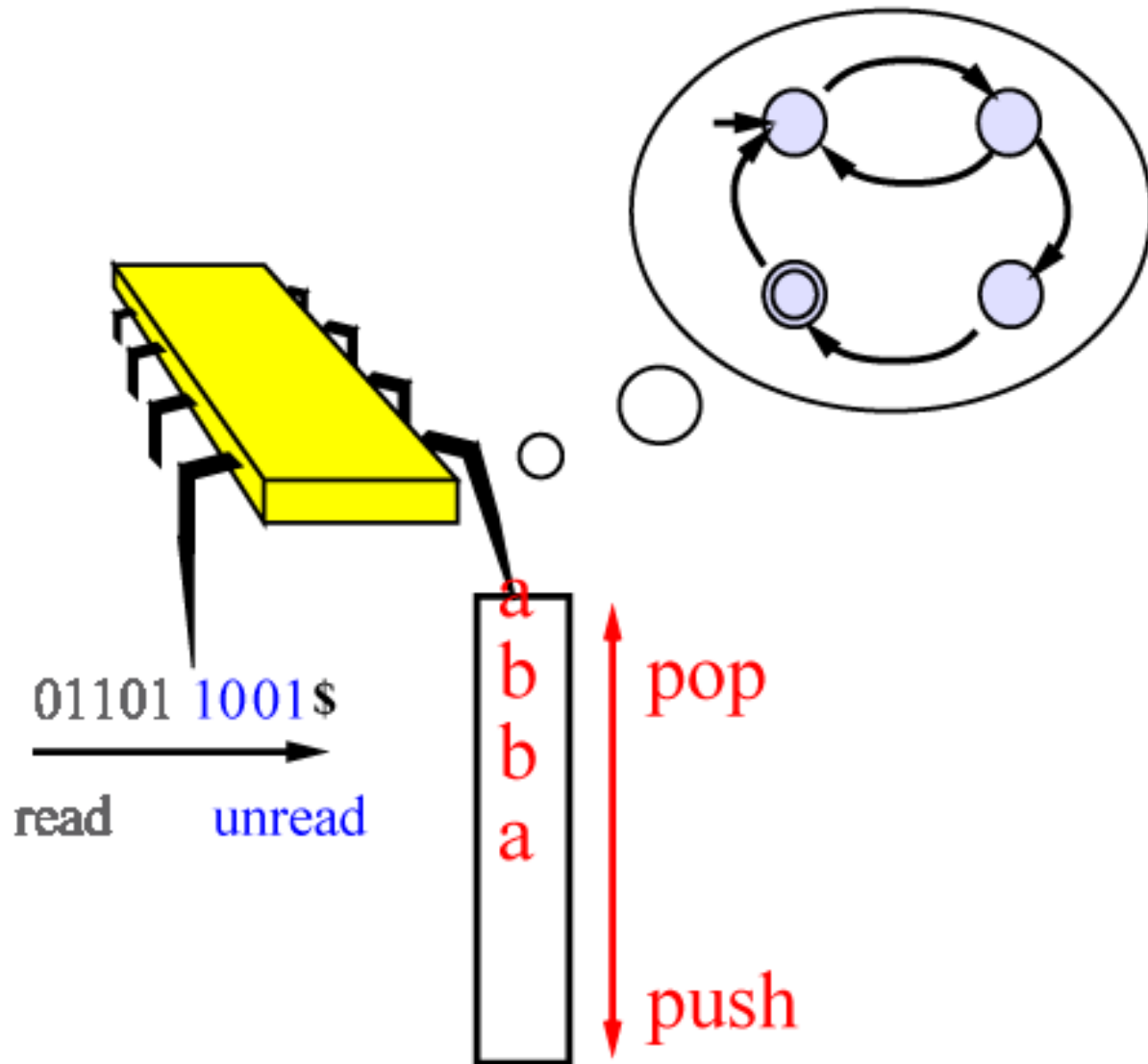
# Comp. Models - Lecture 6, Spring 2011

- Turing Machines
- Turing Machines
- Turing Machines
  
- Alternative Models of Computers
- Multitape TMs, RAMs, Non Deterministic TMs
- The language classes  $\mathcal{R} = \mathcal{RE} \cap \text{co}\mathcal{RE}$
  
- Sipser's book, 3.1, 3.2, & 3.3

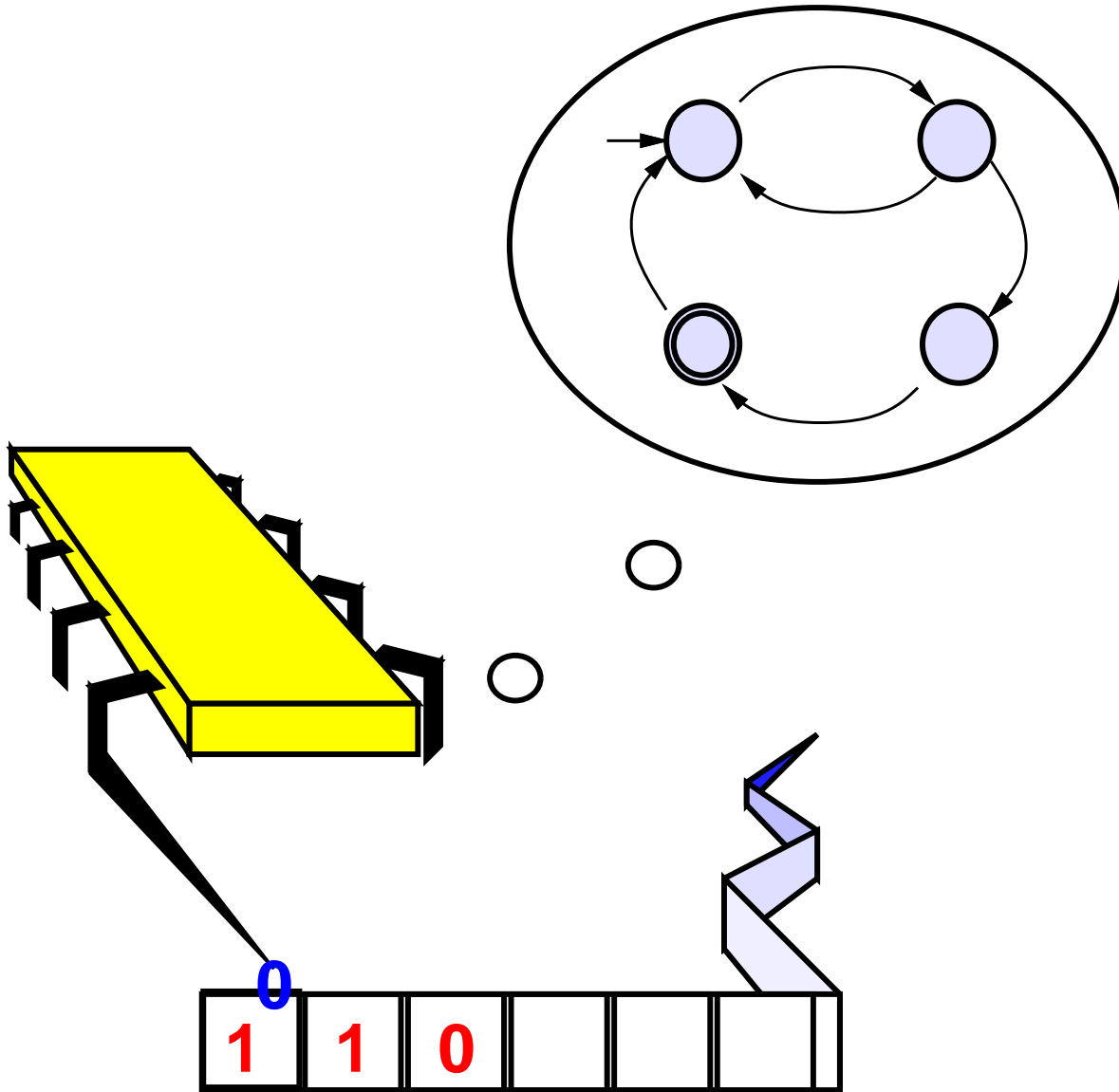
# A Finite Automaton



# A Pushdown Automaton



# A Turing Machine

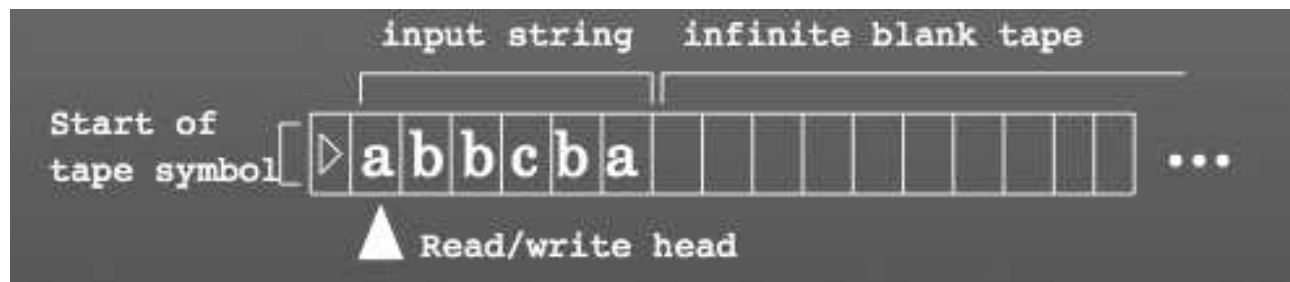


# Turing Machines

- Machines so far (DFA, PDA) read input only once
- **Turing Machines**
  - Can back up over the input
  - Can overwrite the input
  - Can **write** information on tape and **come back** to it later

# Turing Machines

- Input string is written on a tape:



- At each step, machine reads a symbol, and then
  - writes a new symbol, and
  - either moves read/write head to right,
  - or moves read/write head to left

# TM vs. PDA vs. DFA: Differences

- A Turing machine can both write on the tape and read from it.
- A PDA is restricted to reading from the stack in LIFO manner.
- A DFA has no media for writing anything – it must all be in its **finite** state.
- The TM read-write head can move both to the left and to the right
- The TM read-write tape is **infinite** to the right
- The special final (accepting/rejecting) states of TM take **immediate effect** (so the head need not be at some special position)

# Effects of One Step

One step of computation changes

- current state,
  - current head position,
  - and tape contents at current position.
- 
- Each step has very **local**, small effect.
  - But many small effects can accumulate to a meaningful task.



Example  $B = \{w\#w \mid w \in \{0, 1\}^*\}$

- Turing Machine algorithm:
  - Check for single #,
    - If false then **reject**.
  - Zig-zag across the tape, check identical letters, and replace them by  $X$ .
    - If not identical then **reject**.
  - When all the letters left of # are marked  $X$ , check for remaining letters right of #
    - If there remaining letters are **reject**,
    - otherwise **accept**

# Example $B = \{w\#w \mid w \in \{0, 1\}^*\}$

- Input: 0 1 1 0 0 0 # 0 1 1 0 0 0
- $\bar{0}$  1 1 0 0 0 # 0 1 1 0 0 0
- $X \bar{1}$  1 0 0 0 # 0 1 1 0 0 0
- $X$  1 1 0 0 0 #  $\bar{0}$  1 1 0 0 0
- $X$  1 1 0 0 0  $\bar{\#}$   $X$  1 1 0 0 0
- $\bar{X}$  1 1 0 0 0 #  $X$  1 1 0 0 0
- $X \bar{1}$  1 0 0 0 #  $X$  1 1 0 0 0
- $X X \bar{1}$  0 0 0 #  $X$  1 1 0 0 0
- ... ..
- $X X X X X X \# X X X X X X$

# Formal Definition

We start with the transition function

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\} .$$

$\delta(q, a) = (r, b, L)$  means:

- in state  $q$  where head reads tape symbol  $a$ ,
- the machine writes  $b$ , replacing the  $a$  ( $a = b$  is possible),
- enters state  $r$ ,
- and moves the head left  
(this is what the  $L$  stands for).

## Formal Definition (2)

Now the transition function, with a move to the **right**

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\} .$$

$\delta(q, a) = (r, b, R)$  means:

- in state  $q$  where head reads tape symbol  $a$ ,
- the machine writes  $b$ , replacing the  $a$  ( $a = b$  is possible),
- enters state  $r$ ,
- and moves the head right  
(this is what the  $R$  stands for).

## Formal Definition (3)

A Turing machine (TM) is a 7-tuple  $(Q, \Sigma, \Gamma, \delta, q_0, q_a, q_r)$ , where

- $Q$  is a finite set of **states**,
- $\Sigma$  the **input alphabet** not containing the blank symbol,  $\sqcup$
- $\Gamma$  is the **tape alphabet**, where  $\sqcup \in \Gamma$  and  $\Sigma \subset \Gamma$ .
- $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$  is the transition function,
- $q_0 \in Q$  is the **start state**,
- $q_a \in Q$  is the **accept state**, and
- $q_r \in Q$  is the **reject state**.

## Formal Definition (4)

$M = (Q, \Sigma, \Gamma, \delta, q_0, q_a, q_r)$  computes as follows

- an input of length  $n$ ,  $w = w_1w_2 \dots w_n \in \Sigma^*$
- is placed on  $n$  leftmost tape squares, one tape square per input letter
- rest of tape contains blanks  $\sqcup$
- read/write head is on leftmost square of tape
- since  $\sqcup \notin \Sigma$ , leftmost blank indicates end of input.

## Formal Definition (5)

Let  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_a, q_r)$ .

When computation starts,

- $M$  proceeds according to transition function  $\delta$ .
- If  $M$  tries to move head beyond left-hand-end of tape, it doesn't move (still  $M$  does **not** crash).
- Computation continues until  $q_a$  or  $q_r$  is reached,
- otherwise  $M$  runs forever.

# TM Configurations

A TM **configuration** is a convenient notation for recording the state, head location, and tape contents of a TM in a given instant. Think of it as a **snapshot**.

- For example, configuration  $1011q_70111$  means:
- Current state is  $q_7$ ,
- left hand side of tape (to the left of the head) is  $1011$ ,
- right hand side of tape is  $0111$ ,
- and head is on  $0$  (leftmost entry of right hand side).



# Configurations: The Yield Relation

- If  $\delta(q_i, b) = (q_j, c, L)$  then configuration  $uaq_i bv$  **yields** configuration  $uq_j acv$ .
- If  $\delta(q_i, b) = (q_j, c, R)$ , then configuration  $uaq_i bv$  **yields** configuration  $uacq_j v$ .
- Special case (1): When head is at left end and tries to move left, it changes state and writes on tape but **does not move**, so if  $\delta(q_i, b) = (q_j, c, L)$ , configuration  $q_i bv$  yields  $q_j cv$ .
- Special case (2): What happens when head is at right end? We let  $wq_i$  and  $wq_i \sqcup$  denote the same configuration, so **moves to the right** can now be accommodated.

## Configurations: Special Case 2

- 
- Special case (2): What happens when head is at right end? We let  $wq_i$  and  $wq_i\sqcup$  denote the same configuration, so **moves to the right** can now be accommodated.
- In special case (2), the new configuration is **longer** as it “annexed” one blank. This allows configurations to grow in length with computation. Yet at any given moment, they are finitely long.

# More on Configurations

We have

- starting configuration  $q_0w$
- accepting configuration  $w_0q_a w_1$
- rejecting configuration  $w_0q_r w_1$
- halting configurations  $w_0q_a w_1$  and  $w_0q_r w_1$

# Accepting a Language

A Turing machine  $M$  **accepts** an input  $w$  if there is a sequence of configurations  $C_1, C_2, \dots, C_k$  such that

- $C_1$  is start configuration of  $M$  on  $w$ ,
- each  $C_i$  **yields**  $C_{i+1}$ ,
- $C_k$  is an accepting configuration.

The collection of strings **accepted by**  $M$  is called the **language** of  $M$ , and is denoted  $L(M)$ .

# Enumerable Languages

**Definition:** A language  $L$  is called (recursively) enumerable (RE) if some Turing machine accepts  $L$ .  
(In the book called Turing-recognizable)

## Enumerable Languages (2)

On an input,  $w$ , a TM may

- accept
- reject
- loop (run forever)

**Major concern:** In general, we never know if the TM **will** halt.

# Decidable Languages

**Definition:** A TM **decides** a language if for every input  $w \in \Sigma^*$ , the TM halts.

Namely the TM either reaches state  $q_a$  (in case  $w \in L(M)$ ) or it reaches state  $q_r$  (in case  $w \notin L(M)$ ), but it **does not loop**.

Such TM is called a **decider**.

**Definition:** A language  $L$  is **decidable** if some Turing machine decides it.

(In the book called **Turing-decidable** also called **recursive**)

## Example: check if $x = 2^n$

- Function  $\text{POWER2}(x)$
- IF  $x = 1$  return **TRUE**
- ELSE IF  $x \bmod 2 = 1$  return **FALSE**
- ELSE  $\text{POWER2}(x/2)$



Example:  $A = \{0^{2^n} \mid n \geq 0\}$

On input  $w$ :

- **Stage  $I$** : move to the right, erasing every other 0
- If in **stage  $I$**  contains a single 0, then **accept**.
- If after **stage  $I$**  the tape contains more than a single 0, but an odd number of 0, then **reject**.
- Return to the start of the tape
- Go to **stage  $I$** .

**Example:**  $A = \{0^{2^n} \mid n \geq 0\}$

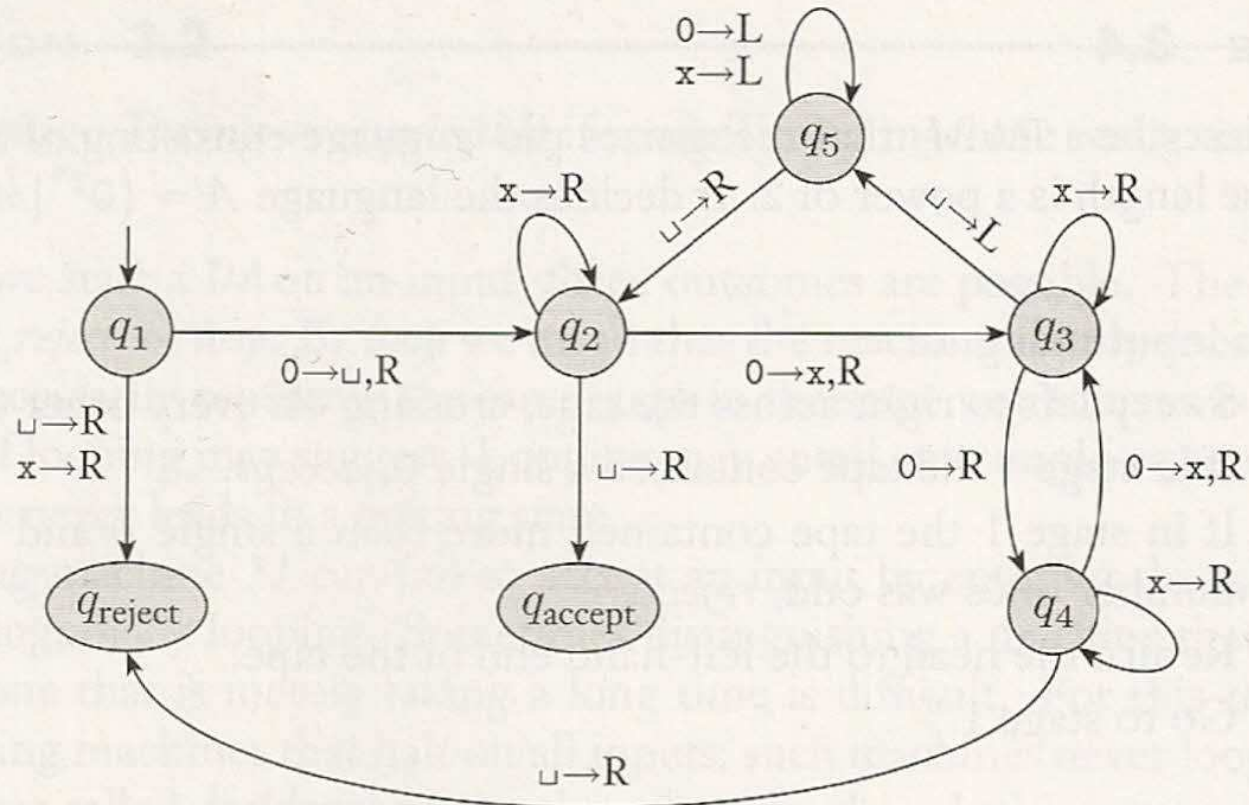
$$M_2 = (Q, \Sigma, \Gamma, \delta, q_1, q_a, q_r)$$

- $Q = \{q_1, q_2, q_3, q_4, q_5, q_a, q_r\}$
- $\Sigma = \{0\}$  input alphabet
- $\Gamma = \{0, x, \sqcup\}$  tape alphabet
- $q_1$  start state
- $q_a$  accept state
- $q_r$  reject state

Example:  $A = \{0^{2^n} \mid n \geq 0\}$

132

CHAPTER 3 / THE CHURCH-TURING THESIS

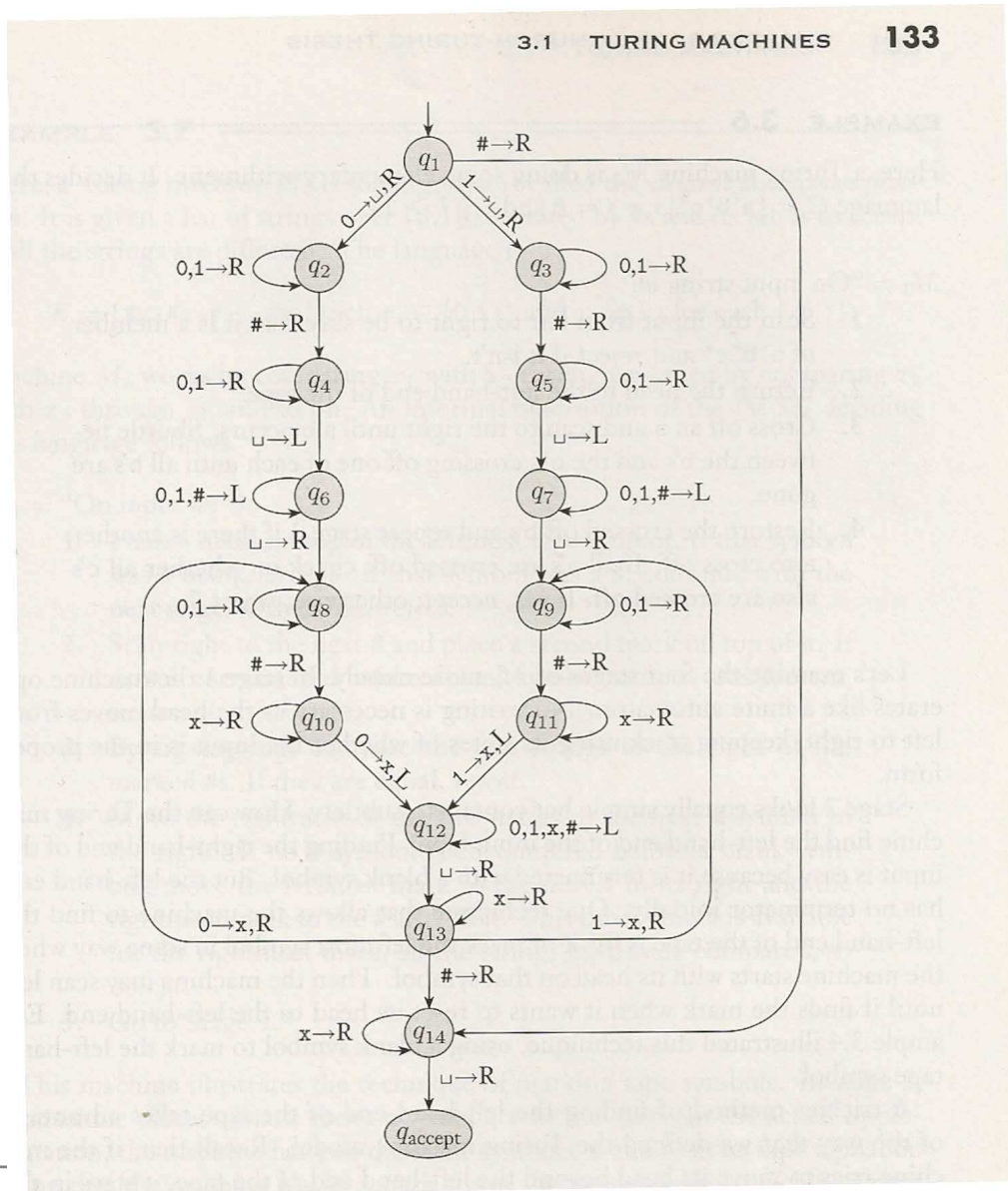


**Example:**  $B = \{w\#w \mid w \in \{0, 1\}^*\}$

$M_1 = (Q, \Sigma, \Gamma, \delta, q_1, q_a, q_r)$ .

- $Q = \{q_1, \dots, q_{14}, q_a, q_r\}$ .
- $\Sigma = \{0, 1, \#\}$  input alphabet
- $\Gamma = \{0, 1, \#, x, \sqcup\}$  tape alphabet
- $q_1$  start state
- $q_a$  accept state
- $q_r$  reject state

Example:  $B = \{w\#w \mid w \in \{0,1\}^*\}$



# Example C

Test  $i \times j = k$  where  $i, j, k \geq 1$

- FUNCTION MULTIPLY( $i, j, k$ )
- $tmp = k$
- WHILE  $i \leq 0$
- $tmp = tmp - j$
- $i = i - 1$
- END WHILE
- IF  $tmp = 0$  return **TRUE**
- ELSE return **FALSE**

## Example C

Here is a high level description of a TM that decides the (non context free) language

$$C = \{a^i b^j c^k \mid i \times j = k \text{ where } i, j, k \geq 1\}$$

- scan from left to right to check that input is  $a^*b^*c^*$
- return to start of tape
- cross off one  $a$  and scan right until  $b$  occurs. Shuttle between  $b$ 's and  $c$ 's, crossing off one of each, until all  $b$ 's are gone.
- **Restore** the crossed-off  $b$ 's and repeat previous step if more  $a$ 's exist. If all  $a$ 's crossed off, check if all  $c$ 's crossed off. If yes, **accept**, otherwise **reject**.

## A Minor, Technical Point

**Question:** To implement algorithm, should be able to tell when a TM is at the left end of the tape.

**Answer** Mark it with a special symbol. When head reads this symbol, TM “knows” it is on the leftmost tape square.



# Example E

Consider the **element distinctness** problem

$$E = \{ \#x_1\#x_2\# \dots \#x_\ell \mid \text{each } x_i \in \{0, 1\}^* \text{ and for each } i \neq j, x_i \neq x_j \} .$$

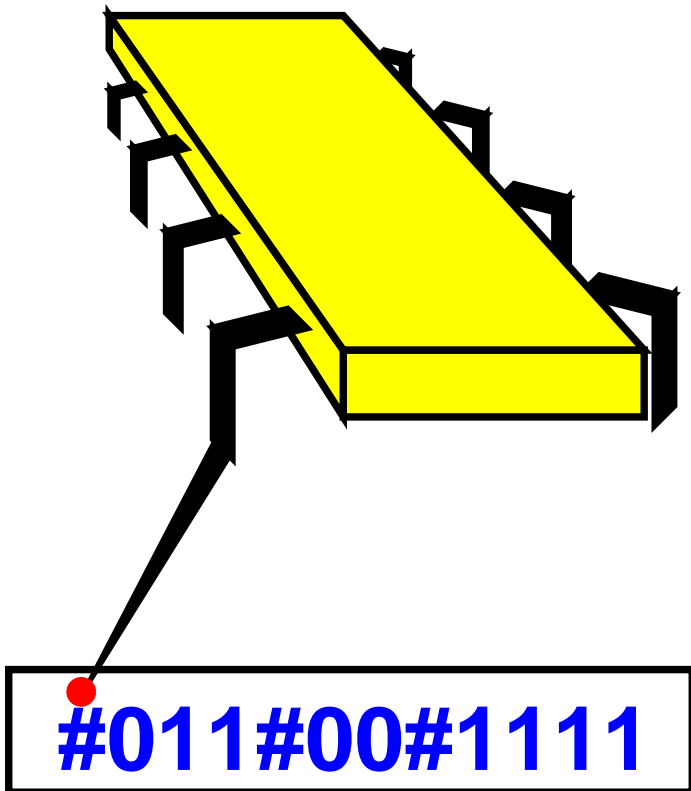
Verbally,

- List of strings in  $\{0, 1\}^*$  separated by  $\#$ 's.
- List is in language (& machine **should** accept) if all strings are **different**.

# Element Distinctness – Solution

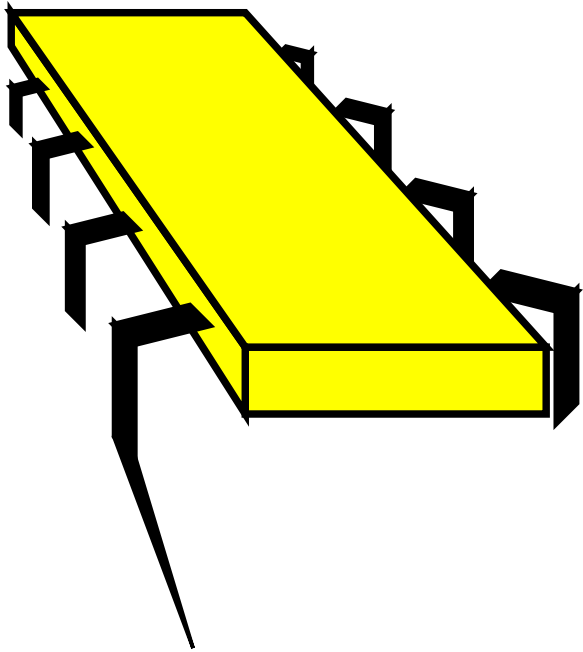
On input  $w$

- place a mark on leftmost tape symbol. If symbol not #, reject.



## Element Distinctness – Solution (2)

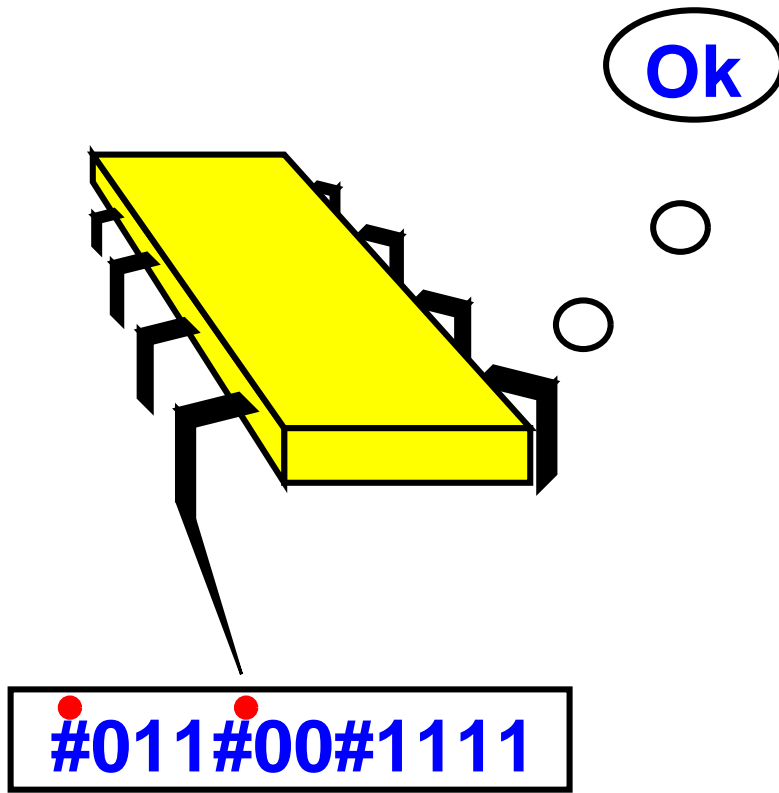
- scan right to next # and place mark on top. If none encountered, reject



#011#00#1111

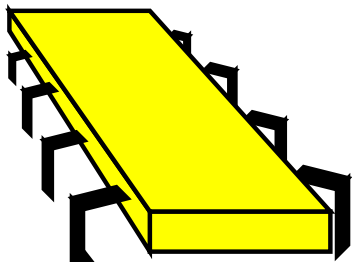
## Element Distinctness – Solution (3)

- By zig-zagging, compare the two strings to the right of the marked #’s. If equal, reject.



# Element Distinctness – Solution (4)

- Iterate:
- Move rightmost mark to next # on right, if any.
- Compare two strings to the right of the marked #'s, as before.
- Otherwise move leftmost mark to next # on right and rightmost mark to # after that.
- If not possible, accept.



#011#00#1111

# Element Distinctness – Solution (end)

**Question:** How do we “mark” a symbol?

**Answer:** For each tape symbol  $\#$ , add tape symbol  $\overset{\bullet}{\#}$  to the tape alphabet  $\Gamma$ .

# TMs Variants

Alternative Turing machine definitions abound.

For example, suppose the Turing machine head is allowed to **stay put**.

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$$

**Question:** Does this add any power?

**Answer:** No. Replace each  $S$  transition with two transitions:  $R$  then  $L$ . (ahmm ... why not vice-versa?)

Important notion here: Two-way **simulation** (model **A** capable of simulating model **B**; model **B** capable of simulating model **A**).

# Multitape Turing Machines

- each tape has its own head
- initially, input string on tape 1 and rest blank

For the transition function:  $\delta : Q \times \Gamma^k \rightarrow Q \times \Gamma^k \times \{L, R\}^k$ ,  
the expression  $\delta(q_i, a_1, \dots, a_k) = (q_j, b_1, \dots, b_k, L, R, \dots, L)$   
means

- machine starts in state  $q_i$
- if heads 1 through  $k$  reading  $a_1, \dots, a_k$ ,
- then machine goes to state  $q_j$ ,
- heads 1 through  $k$  write  $b_1, \dots, b_k$ ,
- and moves each head **right** or **left** as specified.



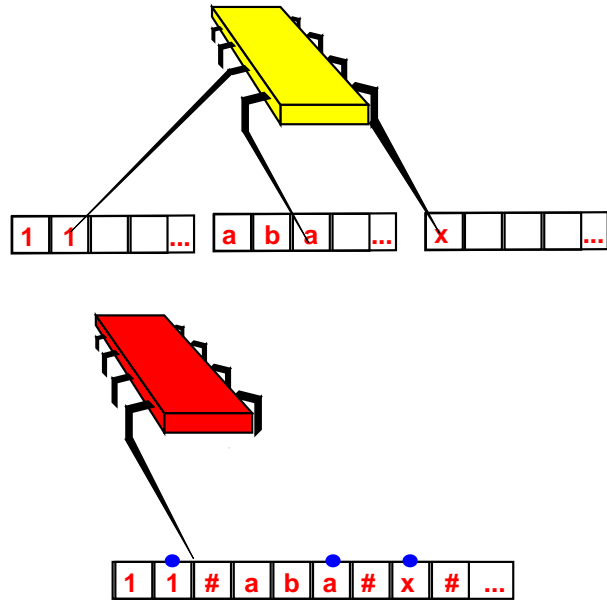
# Equivalence

**Theorem:** A language is enumerable if and only if there is some **multitape** Turing machine that accepts it.

One direction is trivial.

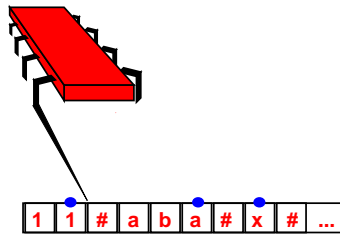
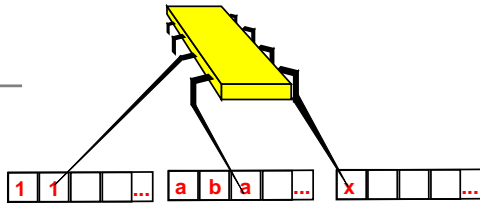
To prove the other direction, we will show how to convert a **multitape** TM,  $M$ , into an equivalent **single-tape** TM,  $S$ .

# Simulation Idea



- $S$  simulates  $k$  tapes of  $M$  by storing them all on a **single tape** with delimiter  $\#$ .
- $S$  marks the current positions of the  $k$  heads by placing
  - “above” the letters in current positions. It “knows” which tape the mark belongs to by counting (up to  $k$ ) from the  $\#$ ’s to the left.

## Simulation (2)



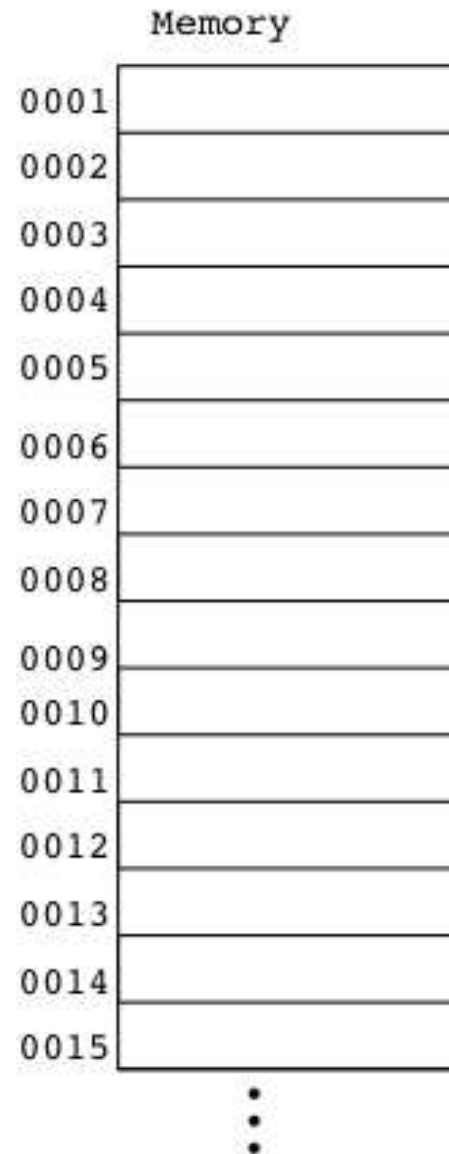
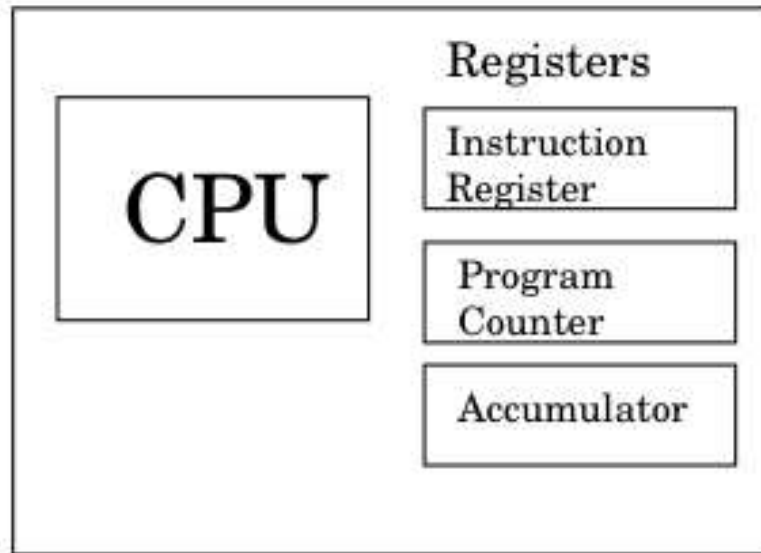
On input  $w = w_1 \cdots w_n$ ,  $S$ :

- writes on its tape  $\# \overset{\bullet}{w_1} w_2 \cdots w_n \# \sqcup \# \sqcup \# \cdots \#$
- scans its tape from first  $\#$  to  $k + 1$ -st  $\#$  to read symbols under “virtual” heads.
- rescans to write new symbols and move heads
- $S$  tries to move virtual head onto  $\#$  when  $M$  is trying to move head onto unused blank square.  $S$  writes blank  $\sqcup$  on tape, and shifts rest of tape one square to the right. ♠

# RAM

- CPU
- 3 Registers (Instruction Register (IR), Program Counter (PC), Accumulator (ACC))
- Memory
- Operation:
  - Increment PC
  - Set  $IR \leftarrow MEM[PC]$
  - Execute **instruction** in IR
  - Repeat
- **Instructions** are typically compare, add/subtract, multiply/divide, shift left/right.
- All instructions are doable on a TM.

# RAM



# RAM Instructions

	Instruction	Meaning
00	HALT	Stop Computation
01	LOAD x	$ACC \leftarrow MEM[x]$
02	LOADI x	$ACC \leftarrow x$
03	STORE x	$MEM[x] \leftarrow ACC$
04	ADD x	$ACC \leftarrow ACC + MEM[x]$
05	ADDI x	$ACC \leftarrow ACC + x$
06	SUB x	$ACC \leftarrow ACC - MEM[x]$
07	SUBI x	$ACC \leftarrow ACC - x$
08	JUMP x	$PC \leftarrow x$
09	JZERO x	$PC \leftarrow x$ if $ACC = 0$
10	JGT x	$PC \leftarrow x$ if $ACC > 0$

# RAM: Example Program

Here is a program that multiplies two numbers (in locations 1000 & 1001), and stores the result in 1002

Memory	Machine Code	Assembly
0001	011000	LOAD 1000
0002	031003	STORE 1003
0003	020000	LOADI 0
0004	031002	STORE 1002
0005	021003	LOAD 1003
0006	090013	JZERO 0013
0007	070001	SUBI 1
0008	031003	STORE 1003
0009	011002	LOAD 1002
0010	041001	ADD 1001
0011	080004	JUMP 4
0013	000000	HALT

# Computers & TMs

**Theorem:** A multi-tape Turing machine can simulate this RAM model.

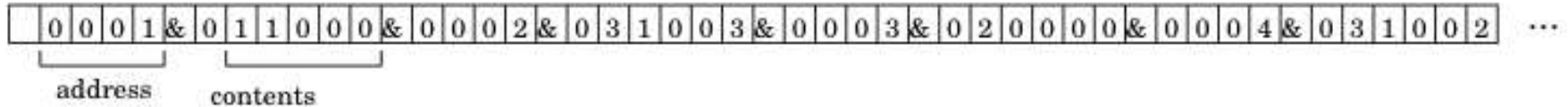
**Idea:** We can simulate the RAM model with a multi-tape Turing machine:

- One tape for each register (IR, PC, ACC)
- One tape for the Memory
- Memory tape will be entries of the form  $\langle \text{address} \rangle$   $\langle \text{contents} \rangle$  in increasing order of addresses.



# Computers & TMs

## Memory



## Instruction Pointer



## Instruction Register



## Accumulator



# Computers & TMs

- Simulating one RAM step on TM:
  - Scan through memory until reach an address that matches the PC
  - Copy contents of memory at that address to the IR
  - Increment PC
  - Based on the instruction code:
    - Copy a value into PC
    - Copy a value into Memory
    - Copy a value into the ACC
    - Perform an arithmetic operation, a shift, or a comparison

# RAMs, Computers & TMs

- A **RAM** can be modeled (simulated) by a Turing Machine.
- Any current machine (architecture, manufacturer, operating system, power supply, etc.) can be modeled by a Turing Machine.
- If there is an algorithm for it, a Turing Machine can do it.
- Note that at this point, we don't care *how long* it might take, just that it can be done.

# Turing Completeness

- A computation model is called “Turing Complete” if it can simulate a (general) Turing Machine.
- Turing Complete  $\Rightarrow$  can compute anything a TM could
  - Of course it might **not** be convenient ...
- Church-Turing Thesis: any computational model can be simulated by a Turing machine.
- More next lecture

# Non-Deterministic Turing Machines

Transition function:

$$\delta : Q \times \Gamma \rightarrow \mathcal{P}(Q \times \Gamma \times \{L, R\})$$

- Computation of a **deterministic** TM can be viewed as a **path** in configuration space.
- Computation of a **non-deterministic** TM (NTM) can be viewed as a **tree** in configuration space.
- NTM accepts an input if **there is** ( $\exists$ ) an accepting branch in its computation tree.
- NTM rejects an input if **all** ( $\forall$ ) branches in its computation tree are either rejecting or infinite (looping).

# Equivalence

**Theorem:** A language is enumerable ( $\mathcal{RE}$ ) if and only if there is some **non-deterministic** Turing machine that accepts it.

One direction is trivial.

To prove the other direction, we will show how to convert a **non-deterministic** TM,  $N$ , into an equivalent **deterministic** TM,  $D$ .

# Simulating Non-Determinism

Basic idea:

- $D$  tries all possible branches
- If  $D$  finds any **accepting** branch, it **accepts**.
- If all branches **reject**,  $D$  **rejects**.
- If all branches **reject** or **loop**,  $D$  **loops**.

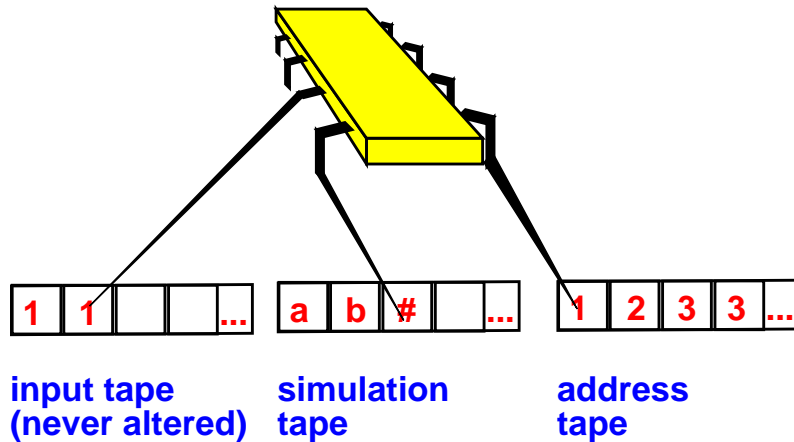
## Simulating Non-Determinism (2)

$N$ 's computation is a tree in the configurations' space.

- each tree branch is a branch of  $N$ 's non-deterministic computation
- each tree node is a configuration of  $N$
- root is starting configuration
- the number of children of each node, denoted by  $b$ , is at most the number of  $N$ 's states, times the size of  $\Gamma$ , times 2 (left/right).
- depth-first search doesn't work (why?)
- breadth-first search does work, as we'll show.



# Simulating Non-Determinism (3)



The simulating machine,  $D$ , has three tapes

- the input tape is never altered (only read from)
- the simulation tape is a copy of  $N$ 's tape
- the address tape keeps track of  $D$ 's location in  $N$ 's computation tree.

# Simulating Non-Determinism (4)

The address tape:

- every node in the tree has at most  $b$  children
- every node in the tree is assigned an address that is a string over the alphabet  $\Sigma_b = \{1, 2, \dots, b\}$
- to get to node with address  $231$ 
  - start at root
  - take **second** child of root
  - take **third** child of current node
  - take **first** child of current node
- ignore meaningless addresses (choices not available for configuration along branch)

## Simulating Non-Determinism (5)

- 1) Initially, the input tape contains  $w$ , and the other two tapes are empty.
- 2) Copy input tape to simulation tape.
- 3) Use simulation tape to simulate  $N$  on input  $w$  on a finite portion of one non-deterministic branch. On each choice, consult the next symbol on address tape.  
**Accept** if accepting configuration reached. Skip to next step if
  - symbols on address tape are exhausted
  - non-deterministic choice is invalid
  - **rejecting** configuration was reached
- 4) Replace string on address tape with the **lexicographically next** string. Go back to Step 2, to simulate this branch of  $N$ 's computation.



# Decidability vs. Enumerability

- **Decidability** is a **stronger notion** than **enumerability**.
- If a language  $L$  is **decidable** then clearly it is **enumerable** (the other direction does **not** hold, as we'll show in a couple of lectures).
- It is also clear that if  $L$  is **decidable** then so is  $\bar{L}$ , and thus  $\bar{L}$  is also **enumerable**.
- Let  $\mathcal{RE}$  denote the class of enumerable languages, and let  $\text{co}\mathcal{RE}$  denote the class of languages whose **complement** is enumerable.
- Let  $\mathcal{R}$  denote the class of decidable languages. Then what we just argued implies  $\mathcal{R} \subseteq \mathcal{RE} \cap \text{co}\mathcal{RE}$ .

## Decidability vs. Enumerability (2)

**Theorem:**  $\mathcal{R} = \mathcal{RE} \cap \text{co}\mathcal{RE}$ .

**Proof:** We should prove the  $\supseteq$  direction. Namely if  $L \in \mathcal{RE} \cap \text{co}\mathcal{RE}$ , then  $L \in \mathcal{R}$ .

In other words, if both  $L$  and its complement are enumerable, then  $L$  is decidable.

Let  $M_1$  be a TM that **accepts**  $L$ .

Let  $M_2$  be a TM that **accepts**  $\bar{L}$ .

We describe a TM,  $M$ , that **decides**  $L$ .

On input  $x$ ,  $M$  runs  $M_1$  and  $M_2$  **in parallel**.

If  $M_1$  accepts,  $M$  **accepts**.

If  $M_2$  accepts,  $M$  **rejects**.

Should now show that indeed  $M$  **decides**  $L$ .

# In Parallel?

**Question:** What does it mean to run  $M_1, \dots, M_k$  in parallel?

- $M$  has two tapes
- One tape has the current configuration of each  $M_i$
- The second tape is a simulation tape.
- $M$ , does for ever,
  - for  $i = 1, \dots, k$ .
    - copies the configuration of  $M_i$ ,
    - simulates a step of  $M_i$ ,
    - writes the new configuration of  $M_i$  back.
    - If this is accepting configuration, **HALT** and return  $i$ .

# Claim

We claim that  $M$  decides  $L$ .

- Every string is in  $L$  or in  $\bar{L}$  (of course not in both).
- Thus either  $M_1$  or  $M_2$  accepts the input  $w$ .
- Consequently, since  $M$  halts whenever  $M_1$  or  $M_2$  accepts,  $M$  always halts, and hence is a decider.
- Moreover,  $M$  accepts strings in  $L$  and rejects strings in  $\bar{L}$ .

Therefore,  $M$  decides  $L$ , so  $L$  is decidable.



# Revised View of the World of Languages

